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High Performance Timing System (HPTS)



Land/Naval HPTS (rear panel connections)

Brandywine's High Performance Timing System (HPTS) is an industry-leading dual redundant modular system designed to provide time and frequency references for various military platforms. This modular system comprises a single rack mounted chassis, into which a number of modules are inserted to provide the required functionality.

The HPTS receives a basic input reference from a GPS receiver, or external source and, in turn supplies a variety of time and frequency signals in a wide variety of available formats. The HPTS is a ruggedized system specified to provide full performance over a wide range of environmental conditions. A unique design feature of the HPTS enables it to distribute time reference signals over a wide area, while providing automatic compensation for propagation delays.

The HPTS has been designed from the outset as a "network centric" product. All features and functions can be monitored and controlled by means of an Ethernet interface.

Two Master Clock Modules (MCM), each utilizing a rubidium or ovenized quartz oscillator, are used to provide redundant time base information for synchronization and system operation. The subsystem components are connected to a backplane bus built into the systems chassis. Output signals are a variety of low voltage analog and digital type signals such as 10MHz, 1PPS, Have Quick and IRIG Time Code.

Key HPTS Features

- Modular Timing System
- Flexible
- Upgradeable
- Redundant
- Hot Swappable Modules
- High Accuracy
- Network-Centric
- Rugged
- Environmentally Qualified
- Automatic Propagation Delay Compensation
- Flexible input reference GPS, Have Quick, IRIG B

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Flight Qualified HPTS (front panel connections)

HPTS Architecture



The HPTS provides an integrated redundant timing system, based on a dedicated high speed backplane that allows time and frequency signals to be distributed and switched between redundant sources.

The HPTS is powered by two independent Power Supply Modules (PSM), each of which can power the entire system. The timing references are generated by independent Master Clock Modules (MCM). Each MCM generates a bi-directional, synchronous data bus signal that is fed to each slot on a passive backplane. The data bus signal contains time of day and control information that can used to generate any required time or frequency output. Output signals are generated by means of output signal modules (OSM) Each OSM monitors both data buses, and will select one MCM based on both availability and/or embedded signaling messages, so that all OSM's use the same MCM as a source. Each MCM monitors the data bus signal from the alternate, and if the off-line module detects that the on-line MCM has failed, it will force all OSM's to switch. Use of a single serial data bus between the MCM's and the OSM's allows an OSM to be remotely located and connected by means of a duplex fiber optic cable. A unique feature of the HPTS is that the MCM can measure the round trip timing delay of the timing reference supplied to each OSM. This propagation delay information is included in the data message to the OSM, so that the timing can be advanced to automatically compensate for delays. This allows the HPTS to provide a high accuracy distributed master system

The system is managed by means of dual 100BaseT Ethernet interfaces. All operating parameters may be set by means of this interface, which uses industry-standard Simple Network Management Protocol (SNMP). The status of both MCM modules and all PSM's and OSM's are monitored by either MCM network interface, or by simplifying device management. Network segregation can also be achieved in each MCM by assigning up to three network addresses to each MCM.

HPTS Benefits

- Automatic propagation delay compensation provides high accuracy time and frequency at the point of use in a distributed environment
- Redundant Time and Frequency Sources provide high availability
- Automatic Switchover in the event of failure
- "Hitless Switching" of outputs when references switch
- Hot Swappable Modules reduce MTTR and increase availability
- Network centric design allows remote management in a "lights out" operating environment
- Flexible architecture provides capability growth as new requirements are defined
- Low cost of ownership due to commonality of modules
- High environmental capability, including low noise reference frequencies under vibration.
- Light-weight, front connector packaging available for aircraft applications with full environmental performance
- High capacity output signal modules provide efficient use of rack space

HPTS Applications

The HPTS has been developed to have the flexibility to suit many applications, including:

- Satellite ground station time and frequency reference
- Airborne master clock system to provide time and frequency references to all mission electronics
- Shipboard master clock system to provide distributed time and frequency across the entire platform
- Test range primary time, frequency and countdown distribution
- Military and government secure communications using either C/A code or SA-ASM P(Y) code GPS receivers
- Telecommunications network synchronization
- Standards and calibration laboratories

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Available HPTS Modules

Master Clock Modules



Front Connector Master Clock Module shown Master clock modules are available in a variety of configurations Available MCM Oscillators Synchronization Sources Oscillator type is specified at time GPS (C/A) Code (opt) of order External Cesium SA-ASM GPS P/(Y) Code - (opt) Internal Rubidium External Have Quick/1PPS (std) Internal OCXO External IRIG B (std) MCM External interfaces J1 Synchronizing inputs External 1PPS External Have Quick IRIG B 124 with IEEE 1344 extensions GPS Antenna (optional) RS232 RS232 console port Monitor operation of HPTS Upload new firmware Connector: MIL-C-38999 type J2 Ethernet Type 100 BaseT Protocols: IP, TCP/IP, UDP, DHCP, NTP, SNMP IP addresses: 6 IP addresses are loaded 3 active addresses are determined by which physical HPTS slot MCM is installed in Connector: RJ45 MIL-C-24682 type MCM controls

Mode select: Auto/manual MCM Display Time display Days thru seconds Led indicators: Power, GPS, IRIG, On-Line, Manual, Holdover, Fault

Power Supply Modules



DC Power Supply Module shown

DC Power supply

Voltage 18-32 V, or 36-72V 120W max Power Quality: MIL-STD-704F compliant Connector: MIL-C-38999 type

AC Power supply

Voltage 85-265 VAC, 50 60 Hz, 120W max Connector: IEC320 or MS 3452W14S-7P

The following modules are available or planned for the HPTS. Specific re-

quirements are easily met by customizing modules to suit new applications.

Output Signal Modules

Baseband Reference Frequency Module Frequencies available: 1,5,10, 64.8, 70, 100 MHz

Level: 13dBm nominal No. of outputs: 5 sinewave, 5 1PPS from direct division Optional 10 sinewave RS422 (1,5 or10 MHz only) These are 3 1PPS signals now Harmonic Distortion: <-40dBc Phase Noise: at 10 MHz Phase Noise (dBc/Hz) Offset Freq. (Hz) With/without vibration 100 ≤ -85 -95dBc -125dBc $10^{1} \leq -100$ -140dBc 10² ≤ -130 10³ ≤ -140 -150dBc -155dBc 104 ≤ -145

Clock Rate Module

Rates Available: N x 1Hz from 1 Hz through 16.384 MHz Level: TTL or RS422 No of outputs: 15 total Rate: All outputs can be independently divided by any integer from the programmed master rate Connector: SMA, D-SUB, Wire wrap available

Pulse Rate Module

Rates Available: 1PPS (std) through 1kPPS Level: 10 V from Lo-Z, 10V from 50 ohm, RS422 No of outputs: 12 single ended, 3 RS422 Connector: SMA (single ended), DB9-F (RS-422)

Modulated Time Code Module

Time Codes: IRIG B124, IEEE-1344 extensions (std) IRIG A. E. G Optional Level: 3Vp-p into 50 ohm load No of outputs: 12 modulated, 3 DCLS at RS422 Connector: SMA (single ended), DB9-F (RS-422)

Have Quick Time Code Output Module

Time Code: Have Quick II per ICD-GPS-060 Level: >2.5V_{0-pk} into 50 ohm load, TTL compatible No of outputs: 15 Connector: SMA (single ended)

Combination Module

This module is often used in conjunction with a remote expansion chassis to provide a limited number of outputs at a remote site. Specifications of each output are as listed above Outputs:

Time Code:

IRIG B modulated, DCLS (RS422) Pulse rates 1PPS (qty 4 single ended, qty 1 RS422) Reference Frequency 10 MHz (aty 4 single ended, aty 1 RS422)) Connector: SMA (single ended) DB9-F (RS-422)

Bus Extender Module

The remote expansion module is used to extend the data bus to a remotely located expansion chassis.

Have Quick II per ICD-GPS-060

Output: Brandywine proprietary data bus (100Mbit/sec) Signal Type: Fiber Optic. Multimode (std), single mode (opt) Connector Type; SC No of Outputs: 6







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Remote Expansion Chassis

Remote Expansion Chassis is used to power one or more Output Signal Modules. It is a 1U rack mount unit that will accept redundant power supplies, and allows up to 2 modules to be installed.

Specifications

System Accuracy

MCM Timing Accuracy when locked to input reference To External Have Quick/1PPS <15ns RMS To IRIG B (modulated) <2usec To GPS (calibrated antenna cable delay) <50ns UTC(USNO) MCM Frequency Accuracy (24 hr avg.) Rubidium Ovenized Quartz <1x10⁻¹² <1x10⁻¹² when locked to input reference <5x10-11 <2x10⁻¹⁰ after 24 hr holdover Short Term Stability 10 MHz output <1x10-11 1sec 10 sec <1x10-11 100 sec <1x10⁻¹⁰ Output Signal Module Accuracy with respect to MCM Main Chassis Remote Location (<2km) 1PPS ±5ns ±20ns Have Quick ±5ns ±20ns IRIG B124 ±250ns ±250ns IRIG B DC ±40ns +60ns Physical Size Width 17.00" (fits standard 19" rack per EIA-310-D) Height 7.00" 5RU 12.00" behind rack (front panel connections) Depth Weight 24 lb nominal Environmental **Operating Temperature** -10 to +50 °C 10°C/hr max rate of change (full accuracy) 10°C/min max rate of change (operating) **Emergency Operating** 70 °C 5 minutes without damage Non-Operating Temperature -40 to +85 °C Humidity 5% to 95% non condensing Altitude Operating -1500 to +11000 ft Non Operating -1500 to +41000ft **Explosive Atmosphere** MIL-STD-810F, Method 511.4, Procedure I Shock 10g 11ms per MIL-STD-810 Method 516.5, Procedure I Bench Handling per MIL-STD-810F, Method 516.5, Procedure VI Acceleration 5g per MIL-STD-810F, Method 513.5, Procedure II Vibration per MIL-STD-810F Operating (Front connector version) 1.3grms Power Spectral Density Frequency 10 Hz 0.0015 40 Hz 0.0015 2000 Hz 0.0005

Endurance 4.6gms Fungus No fungus nutrient materials EMI MIL-STD-461 CE101, CE102, CS101, CS115, CS116, RE101, RE102, RS102, RE103

GPS Receiver Options

Standard Positioning Service (SPS) option Type: 16 Channel C/A Code Frequency: 1575.42 MHz L1 only Acquisition Time Hot Start 8.4 sec (typ.) Warm Start 36 sec (typ.) Cold Start 45 sec (typ.) WAAS support ¹Precise Positioning Service (PPS) SA-ASM option Embedded GPS Receiver: GB-GRAM compliant Type: 12 Channel continuous tracking Code Type: C/A, P(Y) Code Frequency: 1575.42 and 1227.6 MHz L1 and L2 Acquisition Time Hot Start 10 sec (typ.) Warm Start 90 sec (typ.)

15 min (typ.)

KYK-13, KOI-18 DS101, DS102 Red and Black Key capable

Cold Start

Key Loading Interface